

UR

File

Gripper

4:26:22 PM

CCCC ?

Program

Installation

Move

I/O

Log

midhun_pickndplace

Command

Graphics

Structure

Variables

Robot Program

Wait: 5.0

MoveJ

home

MoveJ

app_l2

MoveJ

pick_l2

Gripper Close

MoveJ

app_l2

MoveJ

app_r6

MoveJ

place_r6

Gripper Ope

MoveJ

app_r6

MoveJ

app_r2

MoveJ

pick_r2

Gripper Clos

MoveJ

app_r2

MoveJ

app_l6

Gripper




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Position

100%

Close



Speed

0%



Force

0%

Go to position

Edit action



Complete gripper motion before next action.

Simulation

Real Robot

Speed

100%

Previous

Next

UNIVERSAL ROBOTS