

## RoboDK error issue

Sending command...  
Driver TMDriver.py not running  
Disconnected  
Stopped  
Starting robot driver: /Users/marianneandersen/RoboDK/RoboDK.app/Contents/MacOS/TMDriver.py  
Starting...  
Not started  
Sending command...  
RoboDK Driver for Omron-Techman v1.5.2  
Command CJNT\_FALSE: Get joints modbus  
Command POSXYZ: get position xyz and rot  
Command TOOLXYZ: get tool position xyz and rot  
Command DELTA\_DH: get robot kinematic signature  
Working...  
Working...  
Disconnected  
Connecting to robot 10.0.12.51:5890  
Connecting...  
Connecting...  
TMSTA = Listen node on or off  
Flow is in Listen mode: Listen1  
Waiting for welcome message...  
Ready  
Sending command...  
Working...  
Unexpected error: Traceback (most recent call last):  
Unexpected error: File "/Users/marianneandersen/RoboDK/RoboDK.app/Contents/MacOS/TMDriver.py", line 29, in <module>  
Unexpected error: RunMain()  
Unexpected error: File "C:\RoboDK\api\robot\TMDriver.py", line 1094, in RunMain  
Unexpected error: File "C:\RoboDK\api\robot\TMDriver.py", line 696, in RunDriver  
Unexpected error: File "C:\RoboDK\api\robot\TMDriver.py", line 789, in RunCommand  
Unexpected error: File "C:\RoboDK\api\robot\TMDriver.py", line 466, in WaitRobotMotion  
Unexpected error: File "C:\RoboDK\api\robot\TMDriver.py", line 503, in getJointsModbus  
Unexpected error: File "/Users/marianneandersen/opt/anaconda3/lib/python3.9/site-packages/shiboken2/files.dir/shibokensupport/\_\_feature\_\_.py", line 142, in \_import  
Unexpected error: return original\_import(name, \*args, \*\*kwargs)  
Unexpected error: ModuleNotFoundError: No module named

'pymodbus.client.sync'  
Stopped