

Connection to uFactory Lite6

Robot IP/COM: 192.168.1.156

Robot port: 12345

Connection status:

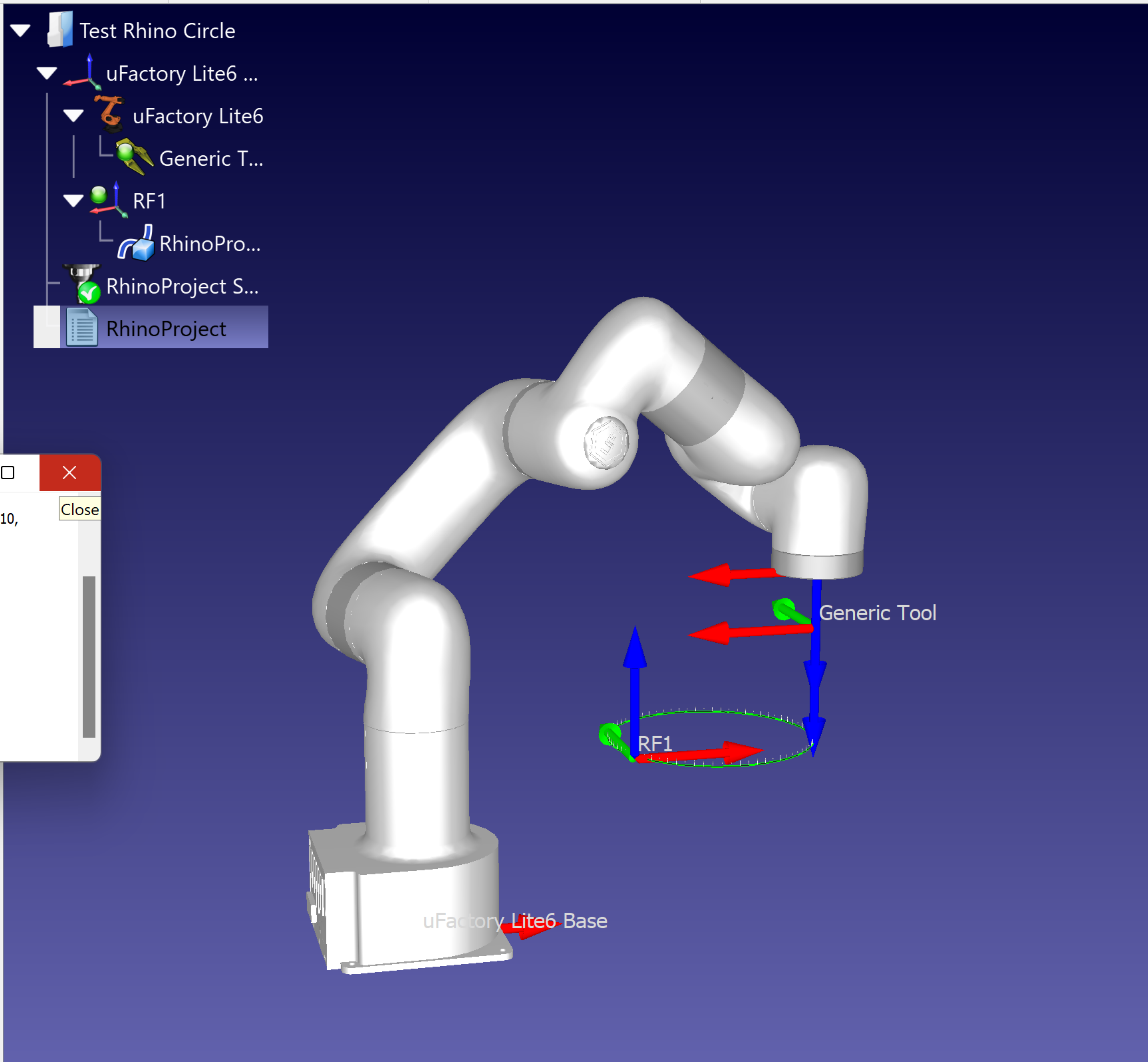
Ready

Remote FTP path:

Remote FTP user name:

Remote FTP password:

Driver: xArmDriver.py



Frame Details: bRef 1

Name: RF1

Visible

Reference position with respect to: uFactory Lite6 Base

[X,Y,Z]mm | Rot[X,Y',Z'']deg - Stäubli/|

200.000	100.000	100.000	0.000	0.000	0.000
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Connection to uFactory Lite6 (l...)

Sending command...

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Using Python version: sys.version_info(major=3, minor=10,
micro=10, releaselevel='final', serial=0)
RoboDK Driver: C:/RoboDK/api/robot
RoboDK Driver for xArm v1.1.4
Disconnected
Working...
RoboDK Driver for xArm v1.1.4
Connecting to robot IP 192.168.1.156
Working...
is_old_protocol: False
version_number: 1.12.10
=====sync_all
[set_state], xArm is ready to move
API Version:6,9,LI1006,DL1000,v1.12.10
Ready
```

Tool Details: BRL

Tool Name: Generic Tool

Visible Show TCP

Tool Center Point with respect to: uFactory Lite6 (flange)

[X,Y,Z]mm | Rot[X,Y',Z'']deg - Stäubli/|

0.000	0.000	50.000	0.000	0.000	0.000
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