

Connection to uFactory Lite6

Robot IP/COM: 192.168.1.156

ping

Robot port: 12345

Explore

Connect

Get Position

Stop

Disconnect

Move Joints

Connection status:

Ready

More options

Show log

Remote FTP path: /

Remote FTP user name:

Remote FTP password:

Driver: xArmDriver.py

Select

Frame Details: bRef 1

Name:

RF1

☒ Visible

Reference position with respect to:

 uFactory Lite6 Base

[X,Y,Z]mm | Rot[X,Y',Z'']deg - Staubli/I







200.000

100.000

100.000

0.000

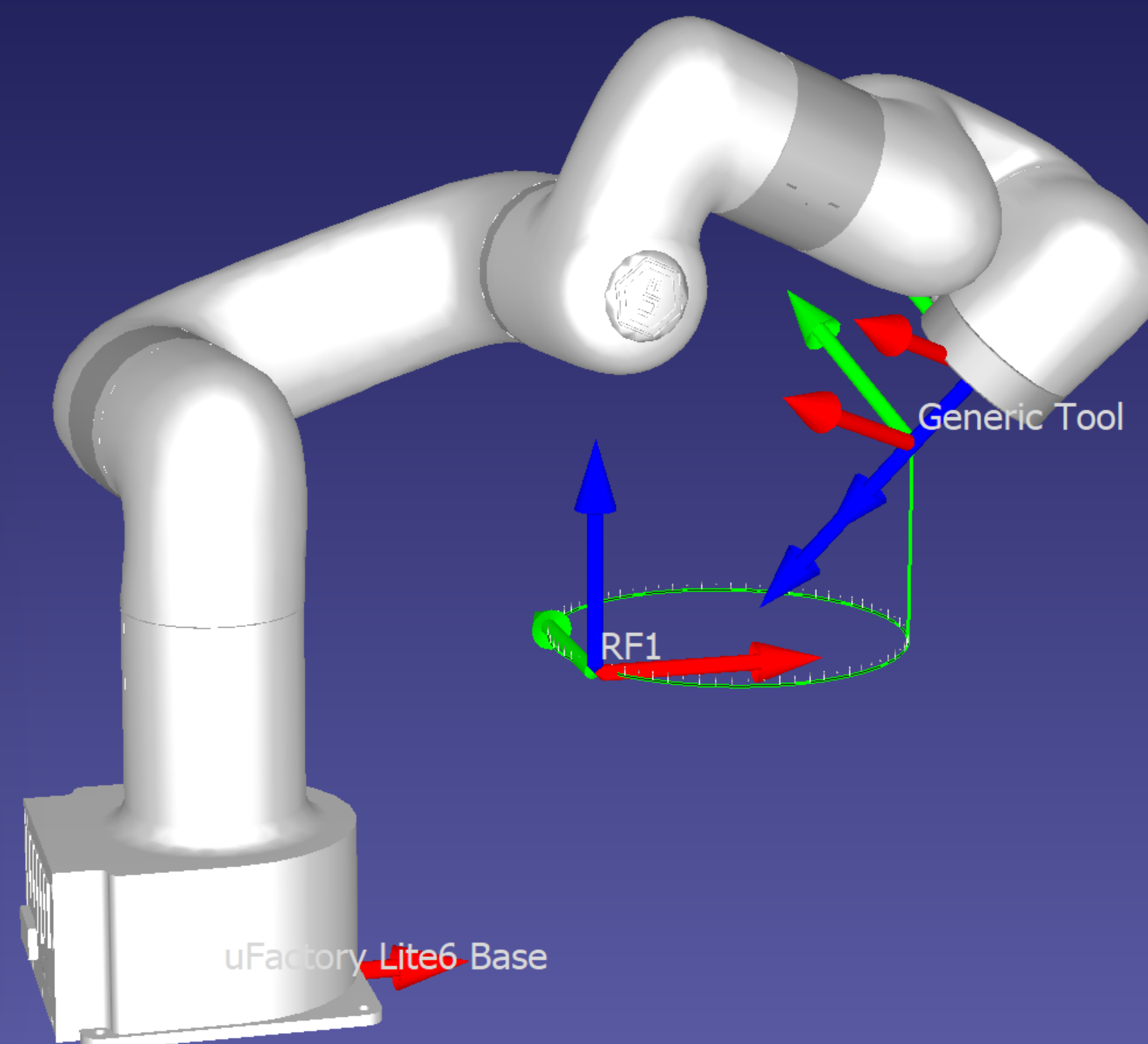
0.000

0.000

```

Connection to uFactory Lite6 (log)
Sending command...
Working...
Ready
Sending command...
Working...
Ready
Sending command...
Working...
ControllerError, code: 21
Error code:21
Disconnected
Sending command...
ControllerError had clean
Working...
RoboDK Driver for xArm v1.1.4
Connecting to robot IP 192.168.1.156
Working...
is_old_protocol: False
version_number: 1.12.10
=====sync_all
[motion_enable], xArm is not ready to move
[set_state], xArm is ready to move
API Version:6,9,LI1006,DL1000,v1.12.10
Ready
Sending command...
Working...
Ready

```



Tool Details: BRL

Tool Name: Generic Tool

☒ Visible ☒ Show TCP

Tool Center Point with respect to uFactory Lite6 (flange)

[X,Y,Z]mm | Rot[X,Y',Z'']deg - Stäubli/i

0.000	0.000	50.000	0.000	0.000	0.000
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