

C: > Users > frank > Documents > RoboDK > Programs > ≡ Viereck_20kg.nc

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1   ; Program Viereck_20kg
2   N00001 F1000 ; Set default speed
3   ; Program generated by RoboDK v5.7.4 for autonox articc6-1803-20kg (AT-00014) on 06/09/2024 16:17:17
4   ; Using nominal kinematics.
5   F60000.000
6   ; Using reference frame: X=556.000 Y=1112.000 Z=480.000 Q1=0.000 Q2=-90.000 Q3=0.000
7   ; Tool frame set to: Werkzeug setzen
8   ; X=0.000 Y=0.000 Z=0.000 Q1=0.000 Q2=0.000 Q3=0.000
9   N00003 M72 T=-1
10  ; N00004 M108 T=... ; Set Drillbit typenumber (not implemented)
11  N00006 G01 X=306.000 Y=862.000 Z=500.000 Q1=180.000 Q2=-0.000 Q3=180.000
12  F3000.000
13  N00007 G01 X=306.000 Y=1362.000 Z=500.000 Q1=180.000 Q2=-0.000 Q3=180.000
14  N00008 G01 X=806.000 Y=1362.000 Z=500.000 Q1=180.000 Q2=-0.000 Q3=180.000
15  N00009 G01 X=806.000 Y=862.000 Z=500.000 Q1=180.000 Q2=-0.000 Q3=180.000
16  N00010 G01 X=306.000 Y=862.000 Z=500.000 Q1=180.000 Q2=-0.000 Q3=180.000
17  F60000.000
18  N00011 G01 X=306.000 Y=862.000 Z=600.000 Q1=180.000 Q2=-0.000 Q3=180.000
19  ; End of program: Viereck_20kg
20  N00012 M30
21  |
```