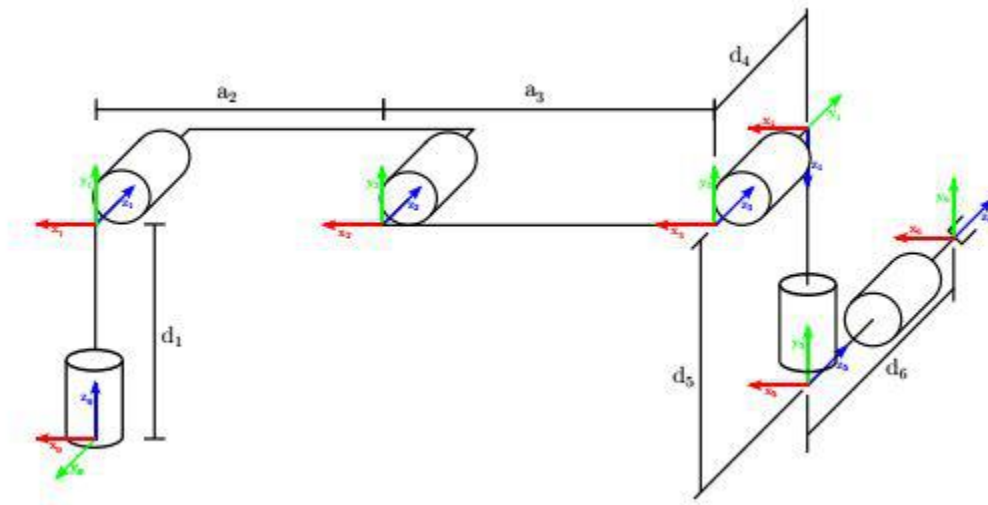


## 1、CR 3 建模



## 2、CR 3\_Modified DH

|        | Theta[rad] | a[m]             | d[m]            | Alpha[rad] |
|--------|------------|------------------|-----------------|------------|
| Joint1 | 0          | 0                | $d_1 = 0.134.8$ | 0          |
| Joint2 | $-\pi/2$   | 0                | 0               | $\pi/2$    |
| Joint3 | 0          | $a_2 = -0.273.8$ | 0               | 0          |
| Joint4 | $-\pi/2$   | $a_3 = -0.230$   | $d_4 = 0.128.8$ | 0          |
| Joint5 | 0          | 0                | $d_5 = 0.116$   | $\pi/2$    |
| Joint6 | 0          | 0                | $d_6 = 0.105$   | $-\pi/2$   |

## 3、CR 3\_Standard DH

|        | Theta[rad] | a[m]             | d[m]            | Alpha[rad] |
|--------|------------|------------------|-----------------|------------|
| Joint1 | 0          | 0                | $d_1 = 0.134.8$ | $\pi/2$    |
| Joint2 | $-\pi/2$   | $a_2 = -0.273.8$ | 0               | 0          |
| Joint3 | 0          | $a_3 = -0.230$   | 0               | 0          |
| Joint4 | $-\pi/2$   | 0                | $d_4 = 0.128.8$ | $\pi/2$    |
| Joint5 | 0          | 0                | $d_5 = 0.116$   | $-\pi/2$   |
| Joint6 | 0          | 0                | $d_6 = 0.105$   | 0          |