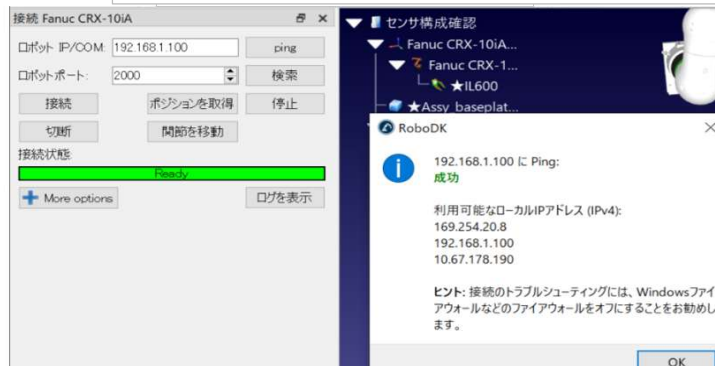


Occasional successful connection after【Stop】→【Ping】
After clicking “Get position”, Not connected

ポジションを取得を押すと、
Not connectedと表示



🔄 接続: Fanuc CRX-10iA (ログ)

Disconnected
Stopped
Starting robot driver: C:/RoboDK/api/robot/FanucSM.exe
Using RoboDK RoboDK v5.6.7
Starting...
Not started
Sending command...
RoboDK driver for Fanuc Socket Messaging v5.2.1
Disconnected
Loading settings: C:/Users/yu19042376/AppData/Roaming/RoboDK-Drivers/FanucSM.exe.ini
AXIS_MAPPING_00 :0
AXIS_MAPPING_01 :1
AXIS_MAPPING_02 :2
AXIS_MAPPING_03 :3
AXIS_MAPPING_04 :4
AXIS_MAPPING_05 :5
AXIS_MAPPING_06 :6
AXIS_MAPPING_07 :7
AXIS_MAPPING_08 :8
AXIS_MAPPING_09 :9
AXIS_MAPPING_10 :10
AXIS_MAPPING_11 :11
AXIS_MAPPING_12 :12
AXIS_MAPPING_13 :13
AXIS_MAPPING_14 :14
AXIS_MAPPING_15 :15
AXIS_MAPPING_16 :16
AXIS_MAPPING_17 :17
AXIS_MAPPING_18 :18
AXIS_MAPPING_19 :19
Trying connection 127.0.0.1:2000...
Sending command...
Not connected
Ready
Trying connection 127.0.0.1:2000...
Sending command...
Not connected
Disconnected
Sending command...
Trying connection 192.168.1.100:2000...
Sending command...
Sending command...
Not connected
Ready
Ready