

Trial Record

1. Reinstall ①RDK_S3.PC, ②GO_MJ.TP, ③GO_ML.TP, ④GO_MC.TP, ⑤GO_PROG.TP.
2. Run RDK_S3.PC (stop at line 76)
3. RDK_S3.PC stopped
4. Enter the IP and Port on RoboDK and connect to the robot.
→Unable to connect.(Same as last time)
Even though clicking **【Get position】** and **【Move Joints】** ,
but there was no response.
(Same as last time)
5. RDK_S3.PC Operate RoboDK in running state (stopped at line 76)
6. Press the RoboDK Connect button
→RDK_S3.PC loops from 507 to 518.

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接続: Fanuc CRX-10iA (ログ)
Driver for RoboDK 5.9.1.25169
Disconnected
Stopped
Starting robot driver: C:/RoboDK/api/robot/FanucSM.exe
Using RoboDK RoboDK v5.9.1
Starting...
RoboDK driver for Fanuc Socket Messaging v5.3.2
Disconnected
Loading settings: C:/Users/User/AppData/Roaming/RoboDK-Drivers/FanucSM.exe.ini
AXIS_MAPPING_00 :0
AXIS_MAPPING_01 :1
AXIS_MAPPING_02 :2
AXIS_MAPPING_03 :3
AXIS_MAPPING_04 :4
AXIS_MAPPING_05 :5
AXIS_MAPPING_06 :6
AXIS_MAPPING_07 :7
AXIS_MAPPING_08 :8
AXIS_MAPPING_09 :9
AXIS_MAPPING_10 :10
AXIS_MAPPING_11 :11
AXIS_MAPPING_12 :12
AXIS_MAPPING_13 :13
AXIS_MAPPING_14 :14
AXIS_MAPPING_15 :15
AXIS_MAPPING_16 :16
AXIS_MAPPING_17 :17
AXIS_MAPPING_18 :18
AXIS_MAPPING_19 :19
Sending command...
Trying connection 192.168.1.100:2000...
Not connected
Trying connection 192.168.1.100:2000...
Not connected
Trying connection 192.168.1.100:2000...
Sending command...
Not connected
Ready
Trying connection 192.168.1.100:2000...
Not connected
Trying connection 192.168.1.100:2000...
Not connected
Trying connection 192.168.1.100:2000...
```